

Network partitioning towards scale-free structure

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Scale-FreeBack



gipsa-lab

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Outline

- 1 Towards scale-freeness
- 2 Tools to solve the problem
- 3 Steady-state preservation
- 4 Minimising transfer function error
- 5 Summary and future work

Outline

- 1 Towards scale-freeness
 - What are scale-free networks?
 - Network partitioning
 - Our objective
- 2 Tools to solve the problem
- 3 Steady-state preservation
- 4 Minimising transfer function error
- 5 Summary and future work

Scale-free networks history

- Introduced by Price in 1965 for citation networks
- Rediscovered by Barabasi and collaborators around 1999
- “Barabasi’s bandwagon”: discovery of the scale-freeness of a lot of networks, like the WWW, social networks, biological networks



D.Price



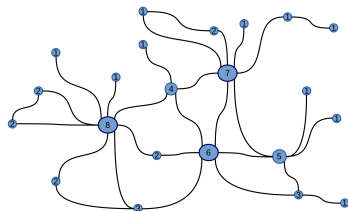
A.-L. Barabasi

Definition of scale-free network

- Degree distribution: distribution of the number of connections per node
- Scale-free networks have power-law $P(k) = k^{-\gamma}$ degree distributions

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Example of a scale-free graph

Degree distribution of a scale-free graph

Properties of scale-free network

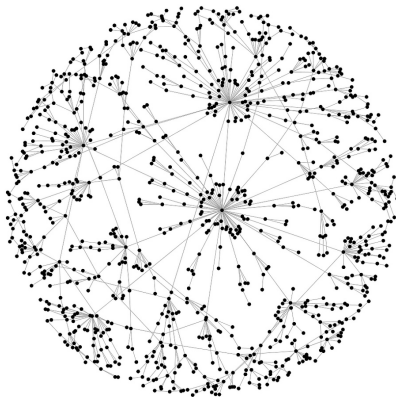
Presence of *hubs* with large degree

Small radius/diameter

Small number of edges

Robust to random node failures

Easy to disconnect



Advantages of scale-freeness for control design

These properties may bring advantages for control design [3]:

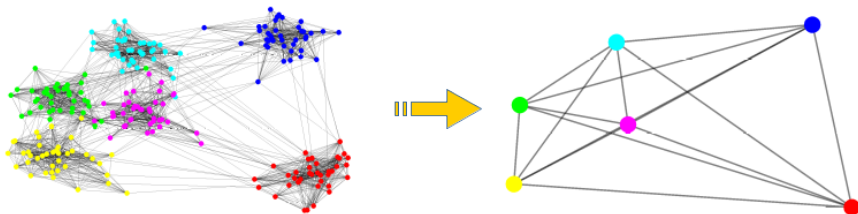
Hubs / Localised control

Small distances / All nodes are easily reachable with few inputs [6]

Few edges / Sparsity of the problem [5]

Network partition

A network partition is a partition of the node set.
From this partition we derive a reduced network



General problem

Partition a network towards a scale-free structure to take advantage of the properties. We also want to preserve a certain similarity.

Given a graph G_0 find $G^?$ solution of the following minimisation problem:

$$G^? = \arg \min_G J_{SF}(G) + J_{sim}(G; G_0) \quad \text{under constraints on } G \quad (1)$$

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Main idea

General algorithm which can be used for any particular case of the general problem.

Consists in iteratively merge a pair nodes in the network.
The algorithm does not provide an optimal solution of the problem.

Merging

We merge two nodes into a super-node and we preserve the connections with the other nodes. The weights on the edges are recomputed.

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We note $G_{i,j}$ the network obtained by merging i, j in the network G

General algorithm

INPUT : initial network G_0 , scale-free coefficient

while : stop

- | (i;j) edge maximising $d_F(G_{i,j}) + J_{\text{sim}}(G_{i,j}; G_0)$ under constraints
- | $G_{k+1} = G_{i,j}$

end

OUTPUT : Final network $G_{k_{\text{nal}}}$

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Example of algorithm

INPUT : initial network G_0 , scale-free coefficient

while : stop

 | (i;j) edge maximising $\phi_F(G_{i,j})$ under $x_i \quad x_j <$

 | $G_{k+1} \quad G_{i,j}$

end

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Steady-state

$$x^? = P^> x^? \quad (2)$$

with P the row-normalised adjacency matrix:

$$P_{i;j} = \frac{A_{i;j}}{\sum_k A_{i;k}};$$

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Specific problem for steady-state preservation

Given a graph G_0 find G^* solution of the following minimisation problem:

$$G^* = \arg \min_G J_{SF}(G) + J_{sim}(G; G_0) \quad \text{under constraints on } G \quad (3)$$

Specific problem for steady-state preservation

Given a graph G_0 find G^* solution of the following minimisation problem:

$$G^* = \arg \min_G J_{SF}(G) \quad \text{under } x_G^* = x_{G_0}^* \quad (4)$$

Weight computation

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Weight computation

Other properties

Within this approach we can also preserve:

Flow property

"What goes in goes out"

$$1A = 1A^0$$

Total mass

$$\sum_{i;j} A_0(i;j) = \sum_{i;j} A_{\text{red}}(i;j)$$

Simulation for steady state preservation

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Model reduction

Model reduction

$$\Sigma : \dot{x} = Ax + Bu \quad \hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^T \hat{x} + PBu \\ x = P^T \hat{x} \end{cases} \quad (5)$$

$$x \in \mathbb{R}^n$$

$$\hat{x} \in \mathbb{R}^m$$

$n = n$ m is the reduction

Transfer function minimisation problem

Given a graph G_0 find $G^?$ solution of the following minimisation problem:

$$G^? = \arg \min_G \quad J_{SF}(G) + kg(s) \hat{g}(s)k_{H_2} \quad (6)$$

where g and \hat{g} are the transfer functions from u to x and from u to \hat{x} respectively

Algorithm

INPUT : initial network G_0

while : stop

| $(i;j)$ edges minimising $J_{SF}(G) + kg(s) \hat{g}(s)k_{H_2}$

| G_{k+1} merge $(i;j)$ in G_k

end

OUTPUT : Final network G_k

Numerical result

TOP: $kg(s)$ $\hat{g}(s)k_{H_2}$ in function of s for different value of α

BOTTOM : Degree distribution for different value of α

In blue : $\alpha = 0$ (only similarity cost function)

In yellow : $\alpha = 1$ (only scale-free cost function)

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Summary and future work

Summary

We developed a general algorithm able to reduce network into a scale-free network and able to preserve properties and a notion of similarity.

We presented two different implementations of this algorithm.


Future work:

- Different similarity costs and physical properties

- Applications to network control

- Adapting to time-varying networks

References

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